## Asymptotics of Lattice Walks Via ACSV

Alexander Kroitor

University of Waterloo

April 2024

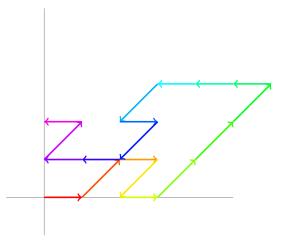


Figure: An Orthant Walk using the Gessel step Set

## Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

### Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

• GFs are a powerful tool in enumerative combinatorics.

### Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

- GFs are a powerful tool in enumerative combinatorics.
- Are amenable to (complex) analytic techniques.

### Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

- GFs are a powerful tool in enumerative combinatorics.
- Are amenable to (complex) analytic techniques.
- Goal of analytic techniques is almost always asymptotics.

### Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

- GFs are a powerful tool in enumerative combinatorics.
- Are amenable to (complex) analytic techniques.
- Goal of analytic techniques is almost always asymptotics.

### Principles of AC

Let A(z) be a generating function with underlying sequence  $a_n$ .

### Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

- GFs are a powerful tool in enumerative combinatorics.
- Are amenable to (complex) analytic techniques.
- Goal of analytic techniques is almost always asymptotics.

### Principles of AC

Let A(z) be a generating function with underlying sequence  $a_n$ .

• **exponential** behaviour of  $a_n \leftrightarrow$  location of singularities

### Definition

Let  $a_n$  be a complex sequence. The **generating function** corresponding to  $a_n$  is

$$A(z)=\sum_{n\geq 0}a_nz^n.$$

- GFs are a powerful tool in enumerative combinatorics.
- Are amenable to (complex) analytic techniques.
- Goal of analytic techniques is almost always asymptotics.

### Principles of AC

Let A(z) be a generating function with underlying sequence  $a_n$ .

- **exponential** behaviour of  $a_n \leftrightarrow$  location of singularities
- **subexponential** behaviour of  $a_n \leftrightarrow kind$  of singularities

Let  $g_n$  count the number of functions that surject [n] onto a set of the form [r].

Let  $g_n$  count the number of functions that surject [n] onto a set of the form [r]. Then

$$G(z)=\sum_{n\geq 0}\frac{g_n}{n!}z^n=\frac{1}{2-e^z}.$$

Let  $g_n$  count the number of functions that surject [n] onto a set of the form [r]. Then

$$G(z)=\sum_{n\geq 0}\frac{g_n}{n!}z^n=\frac{1}{2-e^z}.$$

G(z) has singularities at {log  $2 + 2\pi ik$ }. The singularity with smallest modulus is log 2, which has a simple pole.

Let  $g_n$  count the number of functions that surject [n] onto a set of the form [r]. Then

$$G(z)=\sum_{n\geq 0}\frac{g_n}{n!}z^n=\frac{1}{2-e^z}.$$

G(z) has singularities at {log  $2 + 2\pi ik$ }. The singularity with smallest modulus is log 2, which has a simple pole. Then

$$\frac{g_n}{n!} \sim C\left(\frac{1}{\log 2}\right)^n.$$

Here  $C = \frac{1}{2 \log 2}$  is easily computed.

Let  $g_n$  count the number of functions that surject [n] onto a set of the form [r]. Then

$$G(z)=\sum_{n\geq 0}\frac{g_n}{n!}z^n=\frac{1}{2-e^z}.$$

G(z) has singularities at {log  $2 + 2\pi ik$ }. The singularity with smallest modulus is log 2, which has a simple pole. Then

$$rac{\mathsf{g}_n}{n!} \sim C\left(rac{1}{\log 2}
ight)^n.$$

Here  $C = \frac{1}{2 \log 2}$  is easily computed. If  $H(z) = \frac{1}{(2-e^z)^2}$  then  $\frac{h_n}{n!} \sim Cn \cdot \left(\frac{1}{\log 2}\right)^n$ . There are two main techniques in AC:

## No. 1: Residue Theorem

Let  $G(z) = \sum g_n z^n$  be meromorphic in  $D_r(0)$  and analytic at 0. Let  $\rho_1, \dots, \rho_k$  be a list of all the singularities of G in  $D_r(0)$ . Then

$$g_n = -\sum_{j=1}^k \operatorname{Res}_{z=\rho_j}\left(\frac{G(z)}{z^{n+1}}\right) + \frac{1}{2\pi i} \int_{|z|=r} G(z) \frac{dz}{z^{n+1}}.$$

Here Res is some easily computable operator.

There are two main techniques in AC:

## No. 1: Residue Theorem

Let  $G(z) = \sum g_n z^n$  be meromorphic in  $D_r(0)$  and analytic at 0. Let  $\rho_1, \dots, \rho_k$  be a list of all the singularities of G in  $D_r(0)$ . Then

$$g_n = -\sum_{j=1}^k \operatorname{Res}_{z=\rho_j}\left(\frac{G(z)}{z^{n+1}}\right) + \frac{1}{2\pi i} \int_{|z|=r} G(z) \frac{dz}{z^{n+1}}.$$

Here Res is some easily computable operator.

If G(z) has no singularities we are out of luck!

We describe the general idea.

We describe the general idea.

Suppose that  $G(z)z^{-n-1}$  has a critical point at z = t.

We describe the general idea.

Suppose that  $G(z)z^{-n-1}$  has a critical point at z = t.

• Write as before  $g_n = \frac{1}{2\pi i} \int_{|z|=t} G(z) \frac{dz}{z^{n+1}}$ ,

We describe the general idea.

Suppose that  $G(z)z^{-n-1}$  has a critical point at z = t.

- Write as before  $g_n = \frac{1}{2\pi i} \int_{|z|=t} G(z) \frac{dz}{z^{n+1}}$ ,
- (trim) show that  $g_n \sim \frac{1}{2\pi i} \int_{(|z|=t) \cap B_{\epsilon}(t)} G(z) \frac{dz}{z^{n+1}}$ ,

We describe the general idea.

Suppose that  $G(z)z^{-n-1}$  has a critical point at z = t.

- Write as before  $g_n = \frac{1}{2\pi i} \int_{|z|=t} G(z) \frac{dz}{z^{n+1}}$ ,
- (trim) show that  $g_n \sim \frac{1}{2\pi i} \int_{(|z|=t) \cap B_{\epsilon}(t)} G(z) \frac{dz}{z^{n+1}}$ ,
- (approx.) show that we can approximate

$$\int_{(|z|=t)\cap B_{\epsilon}(t)}G(z)\frac{dz}{z^{n+1}}$$

by replacing  $G(z)z^{-n-1}$  by its leading terms,

We describe the general idea.

Suppose that  $G(z)z^{-n-1}$  has a critical point at z = t.

- Write as before  $g_n = \frac{1}{2\pi i} \int_{|z|=t} G(z) \frac{dz}{z^{n+1}}$ ,
- (trim) show that  $g_n \sim \frac{1}{2\pi i} \int_{(|z|=t) \cap B_{\epsilon}(t)} G(z) \frac{dz}{z^{n+1}}$ ,
- (approx.) show that we can approximate

$$\int_{(|z|=t)\cap B_{\epsilon}(t)}G(z)\frac{dz}{z^{n+1}}$$

by replacing  $G(z)z^{-n-1}$  by its leading terms,

• (compute) compute what's left.

This discussion generalizes to several variables.

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

 can often store "less nice" single-variable GFs in "nice" multivariate ones,

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

- can often store "less nice" single-variable GFs in "nice" multivariate ones,
- can track multiple characteristics at once,

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

- can often store "less nice" single-variable GFs in "nice" multivariate ones,
- can track multiple characteristics at once,
- strict generalization of single-variable GFs.

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

- can often store "less nice" single-variable GFs in "nice" multivariate ones,
- can track multiple characteristics at once,
- strict generalization of single-variable GFs.

Same two techniques exist; must use both in conjunction.

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

- can often store "less nice" single-variable GFs in "nice" multivariate ones,
- can track multiple characteristics at once,
- strict generalization of single-variable GFs.

Same two techniques exist; must use both in conjunction.

Singular set of GF is no longer discrete, now a complex variety.

This discussion generalizes to several variables.

Multivariate GFs are natural to consider:

- can often store "less nice" single-variable GFs in "nice" multivariate ones,
- can track multiple characteristics at once,
- strict generalization of single-variable GFs.

Same two techniques exist; must use both in conjunction.

Singular set of GF is no longer discrete, now a complex variety.

We also need a **direction**; we will only talk about the **main diagonal** of a generating function: given  $F = \sum_{j_1,\dots,j_d} f_{j_1,\dots,j_d} \mathbf{z}^{\mathbf{j}}$  we consider  $\Delta F = \sum_n f_{n,\dots,n} t^n$ . We have a specialized version of the Cauchy Integral Theorem.

Theorem (CIT For Main Diagonal)

Suppose that

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta G(z_1, \cdots, z_d).$$

We have a specialized version of the Cauchy Integral Theorem.

Theorem (CIT For Main Diagonal)

Suppose that

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta G(z_1, \cdots, z_d).$$

### Then

$$f_n = \frac{1}{(2\pi i)^d} \int_{|z_j|=\alpha_j} G(z_1,\cdots,z_d) \frac{dz_1\cdots dz_d}{z_1^{n+1}\cdots z_d^{n+1}}$$

for  $\alpha_j$  sufficiently small for all j.

### Definition (Minimal Critical Points)

Suppose that F = G/H. Then **z** is a **smooth critical point** of *F* if  $H_{z_1}(\mathbf{z}) \neq 0$  and it is a solution to the system of equations

$$H(\mathbf{z})=0, \quad z_1H_{z_1}(\mathbf{z})=\cdots=z_dH_{z_d}(\mathbf{z}).$$

#### Definition (Minimal Critical Points)

Suppose that F = G/H. Then **z** is a **smooth critical point** of *F* if  $H_{z_1}(\mathbf{z}) \neq 0$  and it is a solution to the system of equations

$$H(\mathbf{z})=0, \quad z_1H_{z_1}(\mathbf{z})=\cdots=z_dH_{z_d}(\mathbf{z}).$$

**z** is furthermore **minimal** if there is no **w** such that  $H(\mathbf{w}) = 0$  and  $|w_j| < |z_j|$  for all *j*.

### Definition (Minimal Critical Points)

Suppose that F = G/H. Then **z** is a **smooth critical point** of *F* if  $H_{z_1}(\mathbf{z}) \neq 0$  and it is a solution to the system of equations

$$H(\mathbf{z})=0, \quad z_1H_{z_1}(\mathbf{z})=\cdots=z_dH_{z_d}(\mathbf{z}).$$

**z** is furthermore **minimal** if there is no **w** such that  $H(\mathbf{w}) = 0$  and  $|w_j| < |z_j|$  for all *j*.

Our analysis depends on finding minimal critical points.

## Central Binomial Coefficients

## Consider

$$F(x,y) = \frac{1}{1-x-y} = \sum_{j,k\geq 0} \binom{j+k}{j} x^j y^k.$$

#### Central Binomial Coefficients

Consider

$$F(x,y) = \frac{1}{1-x-y} = \sum_{j,k\geq 0} \binom{j+k}{j} x^j y^k.$$

Then  $V = \{x, y \in \mathbb{C} \mid x + y = 1\}$  and the CP equations are

 $\overset{1-x-y=0}{\underset{-x=-y}{\longrightarrow}} \implies \text{unique minimal CP is } (1/2,1/2).$ 

#### Central Binomial Coefficients

Consider

$$F(x,y) = \frac{1}{1-x-y} = \sum_{j,k\geq 0} \binom{j+k}{j} x^j y^k$$

Then  $V = \{x, y \in \mathbb{C} \mid x+y = 1\}$  and the CP equations are

 $\overset{1-x-y=0}{\underset{-x=-y}{\longrightarrow}} \implies \text{unique minimal CP is (1/2, 1/2)}.$ 

$$\binom{2n}{n} = \frac{1}{(2\pi i)^2} \int_{\substack{|x|=1/2\\|y|=1/2-\epsilon}} \frac{1}{1-x-y} \frac{dxdy}{x^{n+1}y^{n+1}} \\ \sim \frac{1}{2\pi i} \int_{\substack{|x|=1/2\\\arg(x)\in(-\pi/4,\pi/4)}} \frac{dx}{x^{n+1}(1-x)^{n+1}} \\ \sim \frac{4^n}{2\pi} \int_{-\pi/4}^{\pi/4} \frac{1}{1-e^{it}/2} e^{-n(\log(2-e^{it})+it)} dt \sim \frac{4^n}{\sqrt{\pi n}}$$

10 / 31

We can use these techniques to find asymptotics of lattice walk models.

We can use these techniques to find asymptotics of lattice walk models.

## Definition (Lattice Walk Model)

A *d*-dimensional **weighted short-step lattice walk model** consists of:

- a step set  $S\subseteq\{-1,0,+1\}^d\setminus\{(0,\cdots,0)\}$ ,
- a restricting region  $R \subseteq \mathbb{Z}^d$ ,
- a starting point  $p \in R$ ,
- a terminal set  $T \subseteq R$ ,
- a weight  $\omega_s > 0$  for each  $s \in S$  (if unspecified  $\omega_s = 1$ ).

We can use these techniques to find asymptotics of lattice walk models.

## Definition (Lattice Walk Model)

A *d*-dimensional **weighted short-step lattice walk model** consists of:

- a step set  $S \subseteq \{-1, 0, +1\}^d \setminus \{(0, \cdots, 0)\},\$
- a restricting region  $R \subseteq \mathbb{Z}^d$ ,
- a starting point  $p \in R$ ,
- a terminal set  $T \subseteq R$ ,
- a weight  $\omega_s > 0$  for each  $s \in S$  (if unspecified  $\omega_s = 1$ ).

A walk in this lattice walk model consists of a walk that starts at p, stays in R at all times, ends at T, and takes steps using S.

We can use these techniques to find asymptotics of lattice walk models.

## Definition (Lattice Walk Model)

A *d*-dimensional **weighted short-step lattice walk model** consists of:

- a step set  $S \subseteq \{-1, 0, +1\}^d \setminus \{(0, \cdots, 0)\},\$
- a restricting region  $R \subseteq \mathbb{Z}^d$ ,
- a starting point  $p \in R$ ,
- a terminal set  $T \subseteq R$ ,
- a weight  $\omega_s > 0$  for each  $s \in S$  (if unspecified  $\omega_s = 1$ ).

A walk in this lattice walk model consists of a walk that starts at p, stays in R at all times, ends at T, and takes steps using S.

We always let p = 0 and T = R.

We want a convenient way to store S.

## Definition (characteristic polynomial)

The characteristic polynomial of a step set S is

$$\mathcal{S}(\mathsf{z}) = \sum_{s \in S} \omega_s \mathsf{z}^s = \sum_{s \in S} \omega_s z_1^{s_1} \cdots z_d^{s_d}$$

#### Notation

We write  $\overline{z}$  to mean  $z^{-1}$ .

We want a convenient way to store S.

### Definition (characteristic polynomial)

The characteristic polynomial of a step set S is

$$\mathcal{S}(\mathsf{z}) = \sum_{s \in S} \omega_s \mathsf{z}^s = \sum_{s \in S} \omega_s z_1^{s_1} \cdots z_d^{s_d}$$

#### Notation

We write  $\overline{z}$  to mean  $z^{-1}$ .

### Kreweras Step Set

Let  $S = \{(-1,0), (0,-1), (1,1)\}$ . This is the *Kreweras* step set.

$$\overleftarrow{}$$

Then 
$$S(x, y) = \overline{x} + \overline{y} + xy$$
.

Most obvious is  $R = \mathbb{Z}^d$  (so-called **unrestricted walks**). These are too easy!

Most obvious is  $R = \mathbb{Z}^d$  (so-called **unrestricted walks**). These are too easy!

Also natural is  $R = \mathbb{Z}^{d-1} \times \mathbb{N}$  (so-called **half-space walks**). The GFs for these walks are *algebraic* and thus asymptotics are automatic.

Most obvious is  $R = \mathbb{Z}^d$  (so-called **unrestricted walks**). These are too easy!

Also natural is  $R = \mathbb{Z}^{d-1} \times \mathbb{N}$  (so-called **half-space walks**). The GFs for these walks are *algebraic* and thus asymptotics are automatic.

Another natural restricting region is  $R = \mathbb{N}^d$  (orthant walks). We consider this region.

Most obvious is  $R = \mathbb{Z}^d$  (so-called **unrestricted walks**). These are too easy!

Also natural is  $R = \mathbb{Z}^{d-1} \times \mathbb{N}$  (so-called **half-space walks**). The GFs for these walks are *algebraic* and thus asymptotics are automatic.

Another natural restricting region is  $R = \mathbb{N}^d$  (orthant walks). We consider this region.

Note that a *d*-dimensional orthant walk encodes a *multiqueue* system with *d* queues: each point of  $\mathbb{N}^d$  gives the number of people in each queue.

Let  $S = \{(\pm 1, 0), (0, \pm 1).$ 

Let  $f_n$  be the number of orthant walks using S of length n.

Let 
$$S = \{(\pm 1, 0), (0, \pm 1).$$

Let  $f_n$  be the number of orthant walks using S of length n. Then

$$F(t) = \sum_{n \ge 0} f_n t^n = \Delta \left( \frac{(1+x)(1+y)}{1 - txyS(x,y)} \right)$$

Let 
$$S = \{(\pm 1, 0), (0, \pm 1).$$

Let  $f_n$  be the number of orthant walks using S of length n. Then

$$F(t) = \sum_{n \ge 0} f_n t^n = \Delta \left( \frac{(1+x)(1+y)}{1 - txyS(x,y)} \right)$$

For arbitrary step sets the argument we used does not generalize.

Let 
$$S = \{(\pm 1, 0), (0, \pm 1).$$

Let  $f_n$  be the number of orthant walks using S of length n. Then

$$F(t) = \sum_{n \ge 0} f_n t^n = \Delta \left( \frac{(1+x)(1+y)}{1 - txyS(x,y)} \right)$$

For arbitrary step sets the argument we used does not generalize.

If S is mostly symmetric it does.

• A step set S is mostly symmetric if

$$S(z_1, \cdots, z_d) = S(z_1, \cdots, \overline{z}_j, \cdots, z_d) \quad 1 \leq j \leq d-1,$$

meaning S is unchanged if flipped over any of the first d-1 axes.

• A step set S is mostly symmetric if

$$S(z_1, \cdots, z_d) = S(z_1, \cdots, \overline{z}_j, \cdots, z_d) \quad 1 \leq j \leq d-1,$$

meaning S is unchanged if flipped over any of the first d-1 axes. If this is the case we can write

$$S(\mathbf{z}) = \overline{z}_d A(\hat{\mathbf{z}}) + Q(\hat{\mathbf{z}}) + z_d B(\hat{\mathbf{z}})$$

where  $\hat{\mathbf{z}} = (z_1, \cdots, z_{d-1})$  and A, Q, B are highly symmetric.

• A step set S is mostly symmetric if

$$S(z_1, \cdots, z_d) = S(z_1, \cdots, \overline{z}_j, \cdots, z_d) \quad 1 \leq j \leq d-1,$$

meaning S is unchanged if flipped over any of the first d-1 axes. If this is the case we can write

$$S(\mathbf{z}) = \overline{z}_d A(\hat{\mathbf{z}}) + Q(\hat{\mathbf{z}}) + z_d B(\hat{\mathbf{z}})$$

where  $\hat{\mathbf{z}} = (z_1, \cdots, z_{d-1})$  and A, Q, B are highly symmetric.

• A step set S is **highly symmetric** if it is mostly symmetric and also  $S(z_1, \dots, z_d) = S(z_1, \dots, \overline{z}_d)$ . This is equivalent to the condition  $A(\hat{z}) = B(\hat{z})$ .

• A step set S is mostly symmetric if

$$S(z_1, \cdots, z_d) = S(z_1, \cdots, \overline{z}_j, \cdots, z_d) \quad 1 \leq j \leq d-1,$$

meaning S is unchanged if flipped over any of the first d-1 axes. If this is the case we can write

$$S(\mathbf{z}) = \overline{z}_d A(\hat{\mathbf{z}}) + Q(\hat{\mathbf{z}}) + z_d B(\hat{\mathbf{z}})$$

where  $\hat{\mathbf{z}} = (z_1, \cdots, z_{d-1})$  and A, Q, B are highly symmetric.

• A step set S is **highly symmetric** if it is mostly symmetric and also  $S(z_1, \dots, z_d) = S(z_1, \dots, \overline{z}_d)$ . This is equivalent to the condition  $A(\hat{z}) = B(\hat{z})$ .

#### Notation

We also write  $\overline{S}(\mathbf{z}) = z_d A(\hat{\mathbf{z}}) + Q(\hat{\mathbf{z}}) + \overline{z}_d B(\hat{\mathbf{z}})$ .

Let S be a mostly symmetric short-step step set. If  $f_n$  is the number of orthant walks of length n using S then

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta \left( \frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}}) - z_d^2 A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))} \right)$$

Let S be a mostly symmetric short-step step set. If  $f_n$  is the number of orthant walks of length n using S then

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta \left( \frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}}) - z_d^2 A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))} \right)$$

#### Proof.

Use the kernel method.

Let S be a mostly symmetric short-step step set. If  $f_n$  is the number of orthant walks of length n using S then

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta \left( \frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}}) - z_d^2 A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))} \right)$$

#### Proof.

Use the kernel method.

There are 4 different cases to consider.

Let S be a mostly symmetric short-step step set. If  $f_n$  is the number of orthant walks of length n using S then

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta\left(\frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}}) - z_d^2 A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))}\right)$$

#### Proof.

Use the kernel method.

There are 4 different cases to consider. These will be demonstrated by example.

## Highly Symmetric Step Set Asymptotics

In the simplest case where S is highly symmetric, this reduces to

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta\left(\frac{(1+z_1)\cdots(1+z_d)}{1-tz_1\cdots z_d\overline{S}(\mathbf{z})}\right).$$

## Highly Symmetric Step Set Asymptotics

In the simplest case where S is highly symmetric, this reduces to

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta\left(\frac{(1+z_1)\cdots(1+z_d)}{1-tz_1\cdots z_d\overline{S}(\mathbf{z})}\right).$$

## **NSEW Steps**

Consider

$$F(x, y, t) = \frac{G(x, y, t)}{H(x, y, t)} = \frac{(1+x)(1+y)}{1 - txyS(x, y)}$$

where  $S(x, y) = x + \overline{x} + y + \overline{y}$ .

## Highly Symmetric Step Set Asymptotics

In the simplest case where S is highly symmetric, this reduces to

$$F(t) = \sum_{n\geq 0} f_n t^n = \Delta\left(\frac{(1+z_1)\cdots(1+z_d)}{1-tz_1\cdots z_d\overline{S}(\mathbf{z})}\right).$$

## **NSEW Steps**

Consider

$$F(x, y, t) = \frac{G(x, y, t)}{H(x, y, t)} = \frac{(1+x)(1+y)}{1 - txyS(x, y)}$$

where  $S(x,y) = x + \overline{x} + y + \overline{y}$ . This has two minimal CPs:  $\sigma_{-} = (-1, -1, -1/4)$  and  $\sigma_{+} = (1, 1, 1/4)$ . Since G vanishes at (-1, -1) then  $\sigma_{+}$  determines dominant asymptotics.

## NSWE Steps cont.

CIT implies that

$$f_n \sim \frac{1}{(2\pi i)^3} \int_{\substack{|x|=1\\|y|=1}}^{|x|=1} \left( \int_{\substack{|t|=1/4-\epsilon}} \frac{(1+x)(1+y)}{1-txyS(x,y)} \frac{dt}{t^{n+1}} \right) \frac{dxdy}{x^{n+1}y^{n+1}}$$
  
$$\sim \frac{1}{(2\pi i)^2} \int_N \frac{(1+x)(1+y)}{xy} S(x,y)^n dxdy$$
  
$$\sim \frac{4^n}{(2\pi)^2} \int_K 4e^{-n(x^2/4+y^2/4)} dxdy$$
  
$$\sim \frac{4}{\pi} \cdot \frac{4^n}{n}.$$

The techniques in this example generalize to arbitrary highly symmetric step sets.

## Theorem (Melczer Mishna 2016 [MM16])

Suppose S is a highly symmetric step set. If  $s_n$  is the number of walks of length n using S that remains in  $\mathbb{N}^d$  then

$$s_n \sim \left[ rac{S(1)^{d/2}}{\pi^{d/2} (a_1 \cdots a_d)^{1/2}} 
ight] \cdot rac{S(1)^n}{n^{d/2}},$$

where  $a_j$  is the number of steps in S that have *j*-th coordinate 1.

The techniques in this example generalize to arbitrary highly symmetric step sets.

## Theorem (Melczer Mishna 2016 [MM16])

Suppose S is a highly symmetric step set. If  $s_n$  is the number of walks of length n using S that remains in  $\mathbb{N}^d$  then

$$s_n \sim \left[rac{S(1)^{d/2}}{\pi^{d/2}(a_1\cdots a_d)^{1/2}}
ight] \cdot rac{S(1)^n}{n^{d/2}},$$

where  $a_j$  is the number of steps in S that have *j*-th coordinate 1.

#### **Cardinal Directions**

If  $\mathcal{S} = \{\pm e_1, \cdots, \pm e_d\}$  then

$$s_n \sim \left[\frac{(2d)^{d/2}}{\pi^{d/2}}\right] \cdot \frac{(2d)^n}{n^{d/2}}$$

# Mostly Symmetric Step Set Asymptotics - Setup

In the mostly symmetric case we don't have B = A and so can't cancel.

In the mostly symmetric case we don't have B = A and so can't cancel. Furthermore in the expression

$$\frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}})-z_d^2A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))}$$

the factor of B in the denominator behaves uncontrollably.

In the mostly symmetric case we don't have B = A and so can't cancel. Furthermore in the expression

$$\frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}})-z_d^2A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))}$$

the factor of B in the denominator behaves uncontrollably. Instead we write F(t) as the diagonal of

$$\frac{(1+z_1)\cdots(1+z_{d-1})\left(1-tz_1\cdots z_d(Q(\hat{\mathbf{z}})+2z_dA(\hat{\mathbf{z}}))\right)}{(1-z_d)(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))(1-tz_1\cdots z_d(Q(\hat{\mathbf{z}})+z_dA(\hat{\mathbf{z}})))}.$$

In the mostly symmetric case we don't have B = A and so can't cancel. Furthermore in the expression

$$\frac{(1+z_1)\cdots(1+z_{d-1})\left(B(\hat{\mathbf{z}})-z_d^2A(\hat{\mathbf{z}})\right)}{(1-z_d)B(\hat{\mathbf{z}})(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))}$$

the factor of B in the denominator behaves uncontrollably. Instead we write F(t) as the diagonal of

$$\frac{(1+z_1)\cdots(1+z_{d-1})\left(1-tz_1\cdots z_d(Q(\hat{\mathbf{z}})+2z_dA(\hat{\mathbf{z}}))\right)}{(1-z_d)(1-tz_1\cdots z_d\overline{S}(\mathbf{z}))(1-tz_1\cdots z_d(Q(\hat{\mathbf{z}})+z_dA(\hat{\mathbf{z}})))}.$$

This looks awful, but it's easier to deal with the denominator.

## Definition

Let S be a mostly symmetric (and not highly symmetric) step set.

## Definition

Let S be a mostly symmetric (and not highly symmetric) step set.

• S has negative drift if A(1) > B(1),

### Definition

Let S be a mostly symmetric (and not highly symmetric) step set.

- S has negative drift if A(1) > B(1),
- S has positive drift if A(1) < B(1),

### Definition

Let S be a mostly symmetric (and not highly symmetric) step set.

- S has negative drift if A(1) > B(1),
- S has positive drift if A(1) < B(1),
- S has zero drift if A(1) = B(1).

### Definition

Let S be a mostly symmetric (and not highly symmetric) step set.

- S has negative drift if A(1) > B(1),
- S has positive drift if A(1) < B(1),
- S has zero drift if A(1) = B(1).

We can view this as a condition on the vector sum  $\sum \omega_s s \in \mathbb{Z}$ . If this sum is positive S has positive drift etc.

#### Definition

Let S be a mostly symmetric (and not highly symmetric) step set.

- S has negative drift if A(1) > B(1),
- S has positive drift if A(1) < B(1),
- S has zero drift if A(1) = B(1).

We can view this as a condition on the vector sum  $\sum \omega_s s \in \mathbb{Z}$ . If this sum is positive S has positive drift etc.

In each of the different cases the singular variety is differently positioned, and so the asymptotics change.

# Mostly Symmetric Step Set Asymptotics - Negative Drift

The second simplest case is negative drift mostly symmetric.

Negative Drift

Let  $S = \{(-1, -1), (1, -1), (0, 1)\}$ . Then the GF is the diagonal of

$$\frac{(1+x)(1-2t(x^2y^2+1))}{(1-y)(1-t(x^2y^2+y^2+x))(1-t(x^2y^2+1))}$$

## Mostly Symmetric Step Set Asymptotics - Negative Drift

The second simplest case is negative drift mostly symmetric.

Negative Drift

Let  $S = \{(-1, -1), (1, -1), (0, 1)\}$ . Then the GF is the diagonal of

$$\frac{(1+x)(1-2t(x^2y^2+1))}{(1-y)(1-t(x^2y^2+y^2+x))(1-t(x^2y^2+1))}$$

There are now four minimal critical points

$$(1, 1/\sqrt{2}, 1/2), (1, -1/\sqrt{2}, 1/2), (-1, \pm i/\sqrt{2}, -1/2).$$

The numerator vanishes at the last two CPs, implying that the first two give dominant asymptotics. Only one factor of the denominator vanishes (the "smooth" case).

## Mostly Symmetric Step Set Asymptotics - Negative Drift

The second simplest case is negative drift mostly symmetric.

Negative Drift

Let  $S = \{(-1, -1), (1, -1), (0, 1)\}$ . Then the GF is the diagonal of

$$\frac{(1+x)(1-2t(x^2y^2+1))}{(1-y)(1-t(x^2y^2+y^2+x))(1-t(x^2y^2+1))}$$

There are now four minimal critical points

$$(1, 1/\sqrt{2}, 1/2), (1, -1/\sqrt{2}, 1/2), (-1, \pm i/\sqrt{2}, -1/2).$$

The numerator vanishes at the last two CPs, implying that the first two give dominant asymptotics. Only one factor of the denominator vanishes (the "smooth" case). We have

$$s_n \sim \frac{16 + 12\sqrt{2}}{\pi} \cdot \frac{(2\sqrt{2})^n}{n^2} + \frac{-16 + 12\sqrt{2}}{\pi} \cdot \frac{(-2\sqrt{2})^n}{n^2}$$

In general we have the following.

Theorem (Melczer Wilson [MW19])

If S is mostly symmetric with negative drift and  $Q(z) \neq 0$  then

$$s_n \sim C_{
ho} \cdot rac{S(1,
ho)^n}{n^{d/2+1}}.$$

If S is mostly symmetric with negative drift and Q(z) = 0 then

$$s_n \sim C_{
ho} \cdot rac{S(1,
ho)^n}{n^{d/2+1}} + C_{-
ho} \cdot rac{S(1,-
ho)^n}{n^{d/2+1}}.$$

Where  $\rho$ ,  $C_{\rho}$ , and  $C_{-\rho}$  are explicit constants.

In the positive drift case we encounter CPs that lie on the intersection of two factors of the denominator.

## Positive Drift

Let  $S = \{(-1,1), (1,1), (0,-1)\}$ . Then the GF is the diagonal of

$$F(x, y, t) = \frac{(1+x)(1-2txy^2)}{(1-y)(1-t(xy^2+x^2+1))(1-txy^2)}.$$

In the positive drift case we encounter CPs that lie on the intersection of two factors of the denominator.

## Positive Drift

Let  $S = \{(-1,1), (1,1), (0,-1)\}$ . Then the GF is the diagonal of

$$F(x, y, t) = \frac{(1+x)(1-2txy^2)}{(1-y)(1-t(xy^2+x^2+1))(1-txy^2)}.$$

The only minimal CP is (1, 1, 1/3). Two terms in the denominator vanish at this point! This means we are no longer in the "smooth" case. Since the main diagonal is "generic" we are able to take two residues.

## Positive Drift cont.

$$s_{n} \sim \frac{1}{(2\pi i)^{3}} \int_{|x|=1} \left( \int_{\substack{|y|=1-\epsilon\\|t|=1/3-\epsilon}} F(x,y,t) \frac{dydt}{y^{n+1}t^{n+1}} \right) \frac{dx}{x^{n+1}}$$
  
$$\sim \frac{1}{2\pi i} \int_{N} \frac{(x^{2}-x+1)(1+x)}{x(x^{2}+1)} (x+1+1/x)^{n} dx$$
  
$$\sim \frac{\sqrt{3}}{2\sqrt{\pi}} \cdot \frac{3^{n}}{\sqrt{n}}.$$

## Theorem (Melczer Wilson [MW19])

If S is mostly symmetric with positive drift then

$$s_n \sim \left[ \left( 1 - rac{A(1)}{B(1)} 
ight) rac{S(1)^{d/2}}{(2\pi)^{d/2}} \cdot rac{1}{(a_1 \cdots a_d)^{1/2}} 
ight] \cdot rac{S(1)^n}{n^{d/2 - 1/2}}$$

## Mostly Symmetric Step Set Asymptotics - Zero Drift

In the zero drift case A(1) = B(1); we expect the numerator to vanish when z = 1.

#### Zero Drift

Let  $S = \{(-1, -1), (1, -1), 2 \cdot (0, 1)\}$ . Then the GF is the diagonal of

$$F(x, y, t) = \frac{(1+x)(1-2ty^2(x^2+1))}{(1-y)(1-txy(2/y+xy+y/x))(1-ty^2(x^2+1))}.$$

## Mostly Symmetric Step Set Asymptotics - Zero Drift

In the zero drift case A(1) = B(1); we expect the numerator to vanish when z = 1.

#### Zero Drift

Let  $S = \{(-1, -1), (1, -1), 2 \cdot (0, 1)\}$ . Then the GF is the diagonal of

$$F(x, y, t) = \frac{(1+x)(1-2ty^2(x^2+1))}{(1-y)(1-txy(2/y+xy+y/x))(1-ty^2(x^2+1))}.$$

There are four minimal critical points

$$(1, 1, 1/4), (1, -1, -1/4), (-1, \pm i, \mp i).$$

## Mostly Symmetric Step Set Asymptotics - Zero Drift

In the zero drift case A(1) = B(1); we expect the numerator to vanish when z = 1.

#### Zero Drift

Let  $S = \{(-1, -1), (1, -1), 2 \cdot (0, 1)\}$ . Then the GF is the diagonal of

$$F(x, y, t) = \frac{(1+x)(1-2ty^2(x^2+1))}{(1-y)(1-txy(2/y+xy+y/x))(1-ty^2(x^2+1))}.$$

There are four minimal critical points

$$(1, 1, 1/4), (1, -1, -1/4), (-1, \pm i, \mp i).$$

It turns out the contribution from the last three CPs is negligible, and only the first matters. Two terms in the denominator vanish, but this time the main diagonal is "non-generic", and so we are only able to take one residue.

$$s_{n} \sim \frac{1}{(2\pi i)^{3}} \int_{|x|=1} \left( \int_{\substack{|y|=1-\epsilon \\ |t|=1/4-\epsilon}} F(x,y,t) \frac{dydt}{y^{n+1}t^{n+1}} \right) \frac{dx}{x^{n+1}} \\ \sim \frac{1}{(2\pi i)^{2}} \int_{N(1)} \int_{N(1-\epsilon)} \frac{1+x}{2x^{2}y} \cdot \frac{2x-y^{2}(1+x^{2})}{1-y} \overline{S}(x,y)^{n} dxdy.$$

$$s_{n} \sim \frac{1}{(2\pi i)^{3}} \int_{|x|=1} \left( \int_{\substack{|y|=1-\epsilon\\|t|=1/4-\epsilon}}^{|y|=1-\epsilon} F(x,y,t) \frac{dydt}{y^{n+1}t^{n+1}} \right) \frac{dx}{x^{n+1}} \\ \sim \frac{1}{(2\pi i)^{2}} \int_{N(1)} \int_{N(1-\epsilon)}^{} \frac{1+x}{2x^{2}y} \cdot \frac{2x-y^{2}(1+x^{2})}{1-y} \overline{S}(x,y)^{n} dxdy.$$

We cannot take any more residues, and must use saddle-point techniques. Note that at x = y = 1 both the numerator and denominator of  $P(x, y) = \frac{2x - y^2(1 + x^2)}{1 - y}$  vanish.

$$s_{n} \sim \frac{1}{(2\pi i)^{3}} \int_{|x|=1} \left( \int_{\substack{|y|=1-\epsilon\\|t|=1/4-\epsilon}}^{|y|=1-\epsilon} F(x,y,t) \frac{dydt}{y^{n+1}t^{n+1}} \right) \frac{dx}{x^{n+1}} \\ \sim \frac{1}{(2\pi i)^{2}} \int_{N(1)} \int_{N(1-\epsilon)} \frac{1+x}{2x^{2}y} \cdot \frac{2x-y^{2}(1+x^{2})}{1-y} \overline{S}(x,y)^{n} dxdy.$$

We cannot take any more residues, and must use saddle-point techniques. Note that at x = y = 1 both the numerator and denominator of  $P(x, y) = \frac{2x - y^2(1 + x^2)}{1 - y}$  vanish. One can carefully show that P(x, y) has leading term equal to 4, with other terms contributing a negligible amount to asymptotics.

$$s_{n} \sim \frac{1}{(2\pi i)^{3}} \int_{|x|=1} \left( \int_{\substack{|y|=1-\epsilon\\|t|=1/4-\epsilon}}^{|y|=1-\epsilon} F(x,y,t) \frac{dydt}{y^{n+1}t^{n+1}} \right) \frac{dx}{x^{n+1}} \\ \sim \frac{1}{(2\pi i)^{2}} \int_{N(1)} \int_{N(1-\epsilon)} \frac{1+x}{2x^{2}y} \cdot \frac{2x-y^{2}(1+x^{2})}{1-y} \overline{S}(x,y)^{n} dxdy.$$

We cannot take any more residues, and must use saddle-point techniques. Note that at x = y = 1 both the numerator and denominator of  $P(x, y) = \frac{2x - y^2(1 + x^2)}{1 - y}$  vanish. One can carefully show that P(x, y) has leading term equal to 4, with other terms contributing a negligible amount to asymptotics. Thus

$$s_n \sim rac{4}{(2\pi i)^2} \int_N rac{1+x}{2x^2 y} \overline{S}(x,y)^n dx dy \sim rac{4^n}{n} \cdot rac{2\sqrt{2}}{\pi}$$

Dealing with this tricky term gives us the following result.

Dealing with this tricky term gives us the following result.

#### Theorem (K. Melczer [KM24])

Suppose S is a mostly symmetric step set with zero drift. Let  $s_n$  be the number of walks of length n using S that remain in  $\mathbb{N}^d$ . Then

$$s_n \sim \left[ rac{|S|^{d/2}}{\pi^{d/2} (a_1 \cdots a_d)^{1/2}} 
ight] \cdot rac{|S|^n}{n^{d/2}}$$

where  $a_j$  is the number of steps in S that have *j*-th coordinate 1.

# Higher Order Terms

We can find the dominant term for zero drift walks. What about higher order terms?

# Higher Order Terms

We can find the dominant term for zero drift walks. What about higher order terms?

Need to get more terms in the expansion of P(x, y).

## Higher Order Terms

We can find the dominant term for zero drift walks. What about higher order terms?

Need to get more terms in the expansion of P(x, y).

One can show

$$\frac{1}{(2\pi i)^2} \int_{N(1)} \int_{N(1-\epsilon)} \frac{1+x}{2x^2 y} \cdot \frac{2x-y^2(1+x^2)}{1-y} \overline{S}(x,y)^n dxdy$$
  
$$\sim \frac{1}{(2\pi)^2} \int_{K+i(0,\epsilon)} \left(4 + \frac{is^2}{t}\right) e^{-n(s^2/4+t^2/2)} dsdt$$
  
$$\sim \frac{4^n}{n} \cdot \frac{2\sqrt{2}}{\pi} + \frac{4^n}{n^{3/2}} \cdot \frac{1}{\sqrt{\pi}}.$$

To find the higher order asymptotic terms of  $f_n$  we need to be able to evaluate integrals of the form

$$\int_{K+i\epsilon} \frac{A(\mathbf{z})}{\mathbf{z}^{\mathbf{k}}} \exp\left[-n\phi(\mathbf{z})\right] d\mathbf{z}.$$

To find the higher order asymptotic terms of  $f_n$  we need to be able to evaluate integrals of the form

$$\int_{\mathcal{K}+i\epsilon} \frac{A(\mathbf{z})}{\mathbf{z}^{\mathbf{k}}} \exp\left[-n\phi(\mathbf{z})\right] d\mathbf{z}.$$

This is a whole other can of worms.

To find the higher order asymptotic terms of  $f_n$  we need to be able to evaluate integrals of the form

$$\int_{K+i\epsilon} \frac{A(\mathbf{z})}{\mathbf{z}^{\mathbf{k}}} \exp\left[-n\phi(\mathbf{z})\right] d\mathbf{z}.$$

This is a whole other can of worms.

Fin.

# Bibliography

 Alexander Kroitor and Stephen Melczer. Completing the asymptotic classification of mostly symmetric short step walks in an orthant, 2024.
 Stephen Melczer. An Invitation to Analytic Combinatorics. Springer Nature Switzerland, Cham, Switzerland.
 Stephen Melczer and Marni Mishna. Asymptotic lattice path enumeration using diagonals.

Algorithmica, 75(4):782-811, 2016.

 Stephen Melczer and Mark C. Wilson.
 Higher dimensional lattice walks: Connecting combinatorial and analytic behavior.
 SIAM J. Discrete Math., 33(4):2140–2174, 2019.